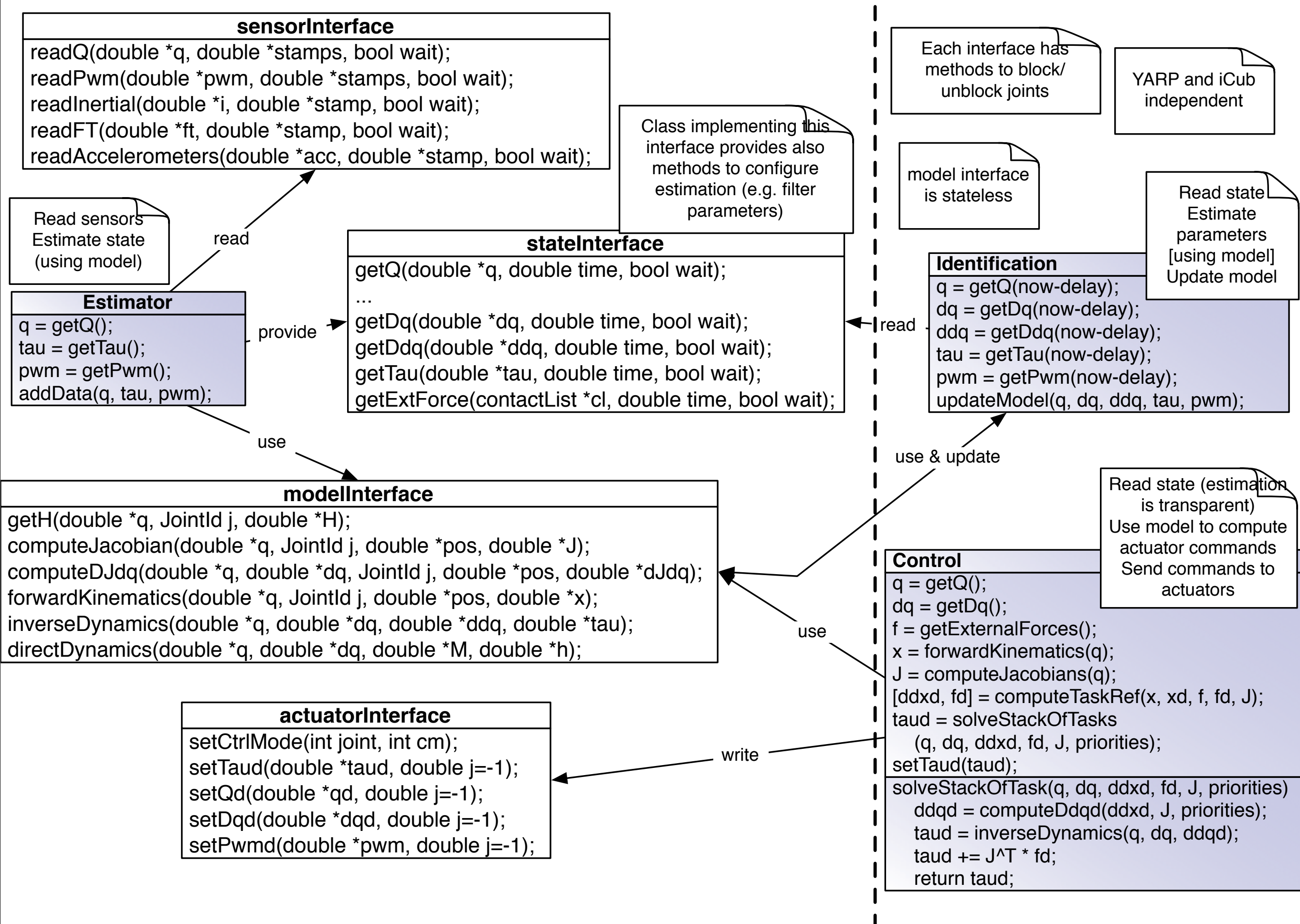


2 Goals

- Write once, run everywhere
- Identify iCub motors => improve joint torque control

Daniele, Silvio, Roberto, Andrea



Adaptive torque control

